

CLAMPING SYSTEMS	
GRIPPER	
To a of prime or to see the top or story to a property of	0
Type of gripper (paralle / angular / concentric)	?
Orientation of gripper (hanging / lying)	7 1
FINGER	
THOLK	
Kind of gripper (friction grip / prismatic jaw)	
Where gripping the piece (outside / inside)	?
Type of conctact (rectangular / round)	?
Angle of prismatic jaw	?
Dimension of the conctact / width of prisma	?
Minimal necessary stroke for finger	?
Height of gripping point from the top edge of gripper	?
Side overhang of gripping point from gripper axis	?
Mass of one finger [kg]	?
Material of the finger at contact face (steel / rubber / other)	?
WORK PIECE	
Material of work piece at contact face (steel / rubber / other)	?
Friction coefficient / Form-fit	?

Mass of work piece [kg]	?
Gripper width (distance between the jaws when gripping piece)	?
Height of center of gravity of the work piece from the top edge of gripper	?
Side overhang of center of gravity from gripper axis	?
LOADS	
Load (send drawing or look to "allowed load data")	?
Direction (condition or lock to "ellowed local data")	?
Direction (send drawing or look to "allowed load data")	· · · · · · ·
Acceleration m/sec2 of the application	?
ANCILLARY CONDITION	
Temperature	?
Application: grinding / assembly / mechanical machining / other	?
Operating pressure	?
Rating IP	?
Pressure plate	?
Safety device? If yes in what version: MC or MA	?
NOTE	